Intelligent Ultra-Wide Band Network

WINLAB | Wireless Information Network Laboratory

Motivation

- Ultra-Wide Band (UWB) is a wireless technology that, despite its long history, can be viewed as new.
- UWB can transmit data over wide frequency spectrum, therefore, unused frequency capacities can be used ideally.
- Given the robustness of UWB, it can be used where different wireless connection technologies overlap.

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UWB is therefore one of the key technologies for particularly demanding application areas such as the Internet of Things (IoT)



Ultra-Wide Band

- Ultra-Wide Band is a **fast, stable, short-range** and **low** power radio protocol.
- UWB utilizes a wider frequency range and is defined by bandwidth which exceeds the lesser of 500 MHz or 20% of the arithmetic center frequency.
- FCC Regulations:
 - Power Spectral Density (PSD) is limited to – 41.25 dBm/MHz.
- Applications:
- Industry
- Sports
- Smart Homes
- And many more...



Clock

- Every individual sensor in a network has its own clock can be represented C(t) = t, t is ideal or reference time.
- Clock will drift away from the ideal time even if it is initially perfectly tuned.
- $C_i(t) = \Theta + f.t$ (Θ clock offset and *f* is clock skew)



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Clock Synchronization

- Clock Synchronization is a procedure for providing a common notion of time across a distributed system.
- Various random delays and limited/non rechargeable power sources make clock synchronization difficult.
- Clock Synchronization is crucial for number of fundamental operations performed by Wireless Sensor Networks like:
 - **Data fusion** Process and integrate the collected data.
 - **Power Management** Duty cycling helps the nodes to Ο save energy resources
 - **Transmission Scheduling** Scheduling requires clock Ο synchronization

MATLAB Simulation

- MATLAB simulation for basic communication in baseband with delay computation
- Below is the block diagram for transmission and reception using root raised cosine filter with fixed delay computation



Simulation Parameters

Data symbols for different coding sequence (Random, Barker, PN) as input to the transceiver.

	Figure 1: Impulse Response 🗙
2 Random [1 1 -1 -1] sequence (Symbols = 16)	Nsym = 6; % Filter span in symbol durations Impulse Response
	beta = 0.25; % Roll-off factor sampsPerSvm = 4; % Upsampling factor
	Xintializing RaisedCosineTransmitFilter
-2 ₀ 2 4 6 8 10 12 14 16 18	txfilter = comm.RaisedCosineTransmitFilter(0.4
Time (ms) Barker sequence (Symbols = 13)	'Shape', 'Square root', 'RolloffFactor', beta,
	'FilterSpanInSymbols', Nsym, 0
	fvtool(txfilter, 'Analysis', 'impulse')
-2 0 2 4 6 8 10 12 14 16 18 Time (ms) PN sequence (Symbols = 15)	0.1
	-0.1
-2 4 6 8 10 12 14 16 18 Time (ms)	0 5 10 15 20 Samples





[1] Y. Wu, Q. Chaudhari and E. Serpedin, "Clock Synchronization of Wireless Sensor Networks," in IEEE Signal Processing Magazine, vol. 28, no. 1, pp. 124-138, Jan. 2011



Simulation Results

Mean Absolute Error, Root Mean Squared Error (RMSE) for delay Error plotted for different values of SNR (1000 iterations for each SNR value. Below is SNR requirement for different coding scheme to maintain accuracy of 1ms.

- \circ Barker = -8 dB \circ **PN = -8.9 dB**
- Random seq $([1 \ 1 \ -1 \ -1..]) = -5.4 \text{ dB}$

Thus from above plot PN sequence stands out most resilient (out of three) for our accuracy level (1ms)

Conclusion and Future Work

- Delay computation is adversely impacted with deteriorating values of SNR. So, depending on channel, SNR should be maintained at higher values.
- Choosing the right coding scheme also plays important role in delay computations.
- We can use cross-correlation between transmitted and received signal to compute delay for a short training sample and correct the actual data with computed delay.

Future Work:

- Run simulation to compute/estimate random delays for AWGN channel and UWB frequency range.
 - Simulate clock synchronization scheme for a small
 - UWB wireless sensor network.

References

[2] S. P. Chepuri, R. T. Rajan, G. Leus and A. van der Veen, "Joint Clock Synchronization and Ranging: Asymmetrical Time-Stamping and Passive Listening," in IEEE Signal Processing Letters, vol. 20, no. 1, pp. 51-54, Jan. 2013

[3] B. M. Sadler and R. J. Kozick, "A Survey of Time Delay Estimation Performance Bounds," Fourth IEEE Workshop on Sensor Array and Multichannel Processing, 2006., Waltham, MA, 2006, pp. 282-288

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