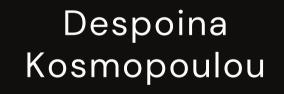
mmWave Channel Analysis Campaign

Despoina Kosmopoulou, John Allen Manego, Mark Moroney, Prakshab Adhikari, Archisa Arora

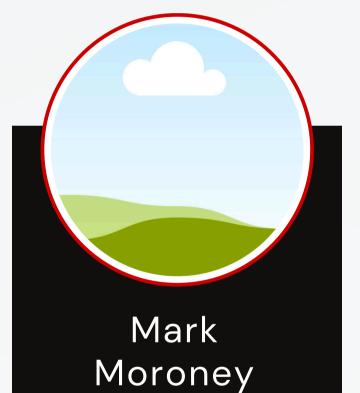




Meet the team









John Allen Manego

Explore and understand the behaviors of the FR2 range (24.25 - 52.6 GHz) to model impacts on adjacent frequency ranges.

Experiment 1

Measuring the Power Distance Relationship of a Signal ML Model to Detect Water Obstruction of OFDM Signals

Overview

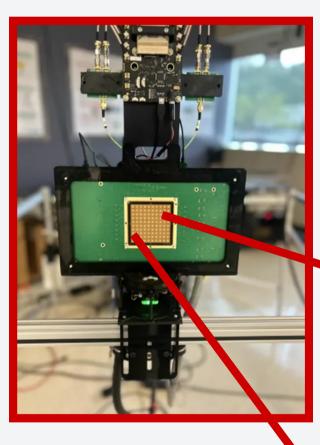
Experiment 2

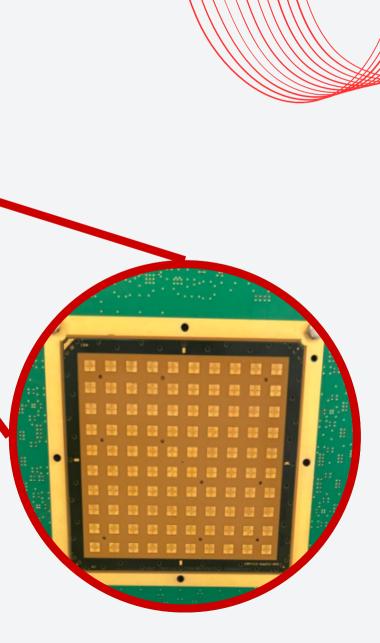
Hardware

Phased-Array Antenna Module (PAAM)

- Adjusts the phase of signals transmitted by an array of antennas to achieve rapid beamforming to enhance signal strength
- Can change direction of signal transmission very rapidly, on the order of the speed of the internal computer clock

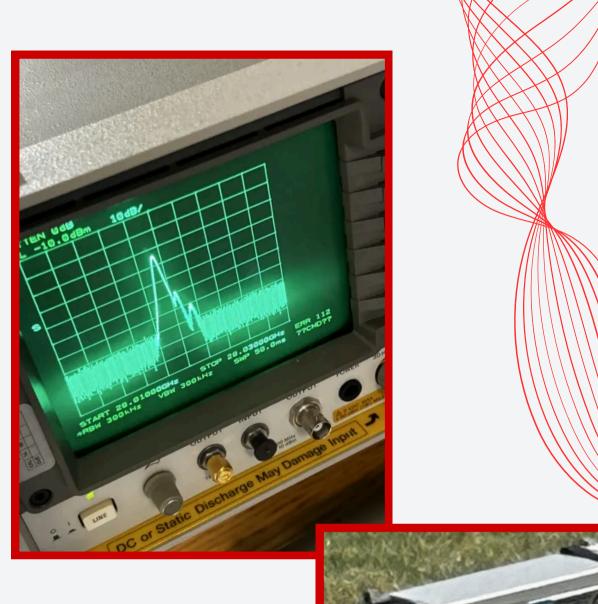






Hardware Spectrum Analyzer (SA)

- Used for frequency-domain analysis of a received signal
- Crucial for detecting signal interference, bandwidth, and assessing signal quality

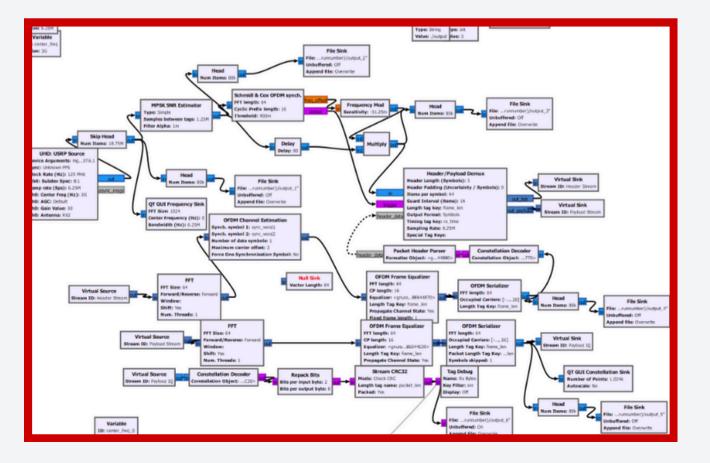




Software GNU Radio

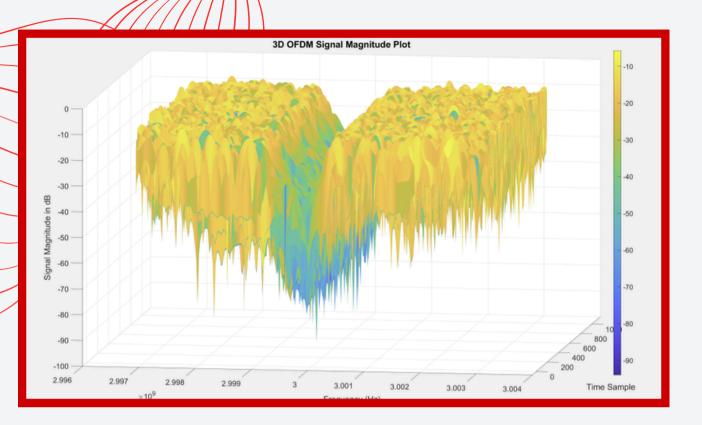
- GNU Radio is an open-source software development toolkit for implementing and simulating software-defined radios (SDRs)
- Allows for the creation of reconfigurable radio systems for a variety of applications
- For our purposes, we created flowgraphs for the RX(Receiver) and TX(Transmitter)
 operations of the PAAMs.

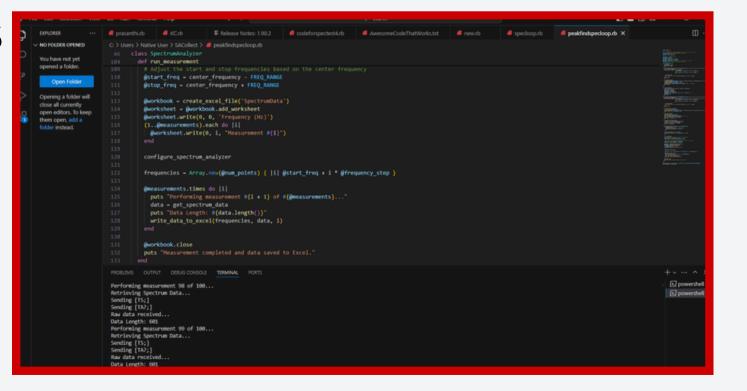




Software Ruby & Matlab

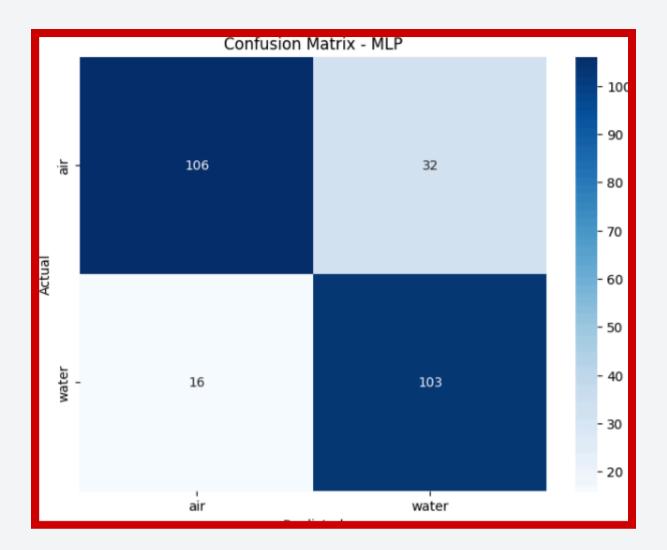
- "Screenshot" information from the Spectrum Analyzer
 - Visualizing on computer
 - Collecting points of data to compare different powers at different distances
 - Create graphs to see key features of the data (peaks, skirts, etc.)
- Run mathematical analysis to come to conclusive results

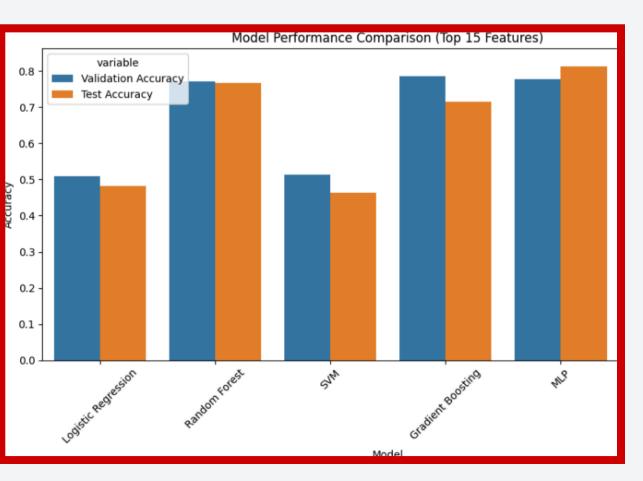


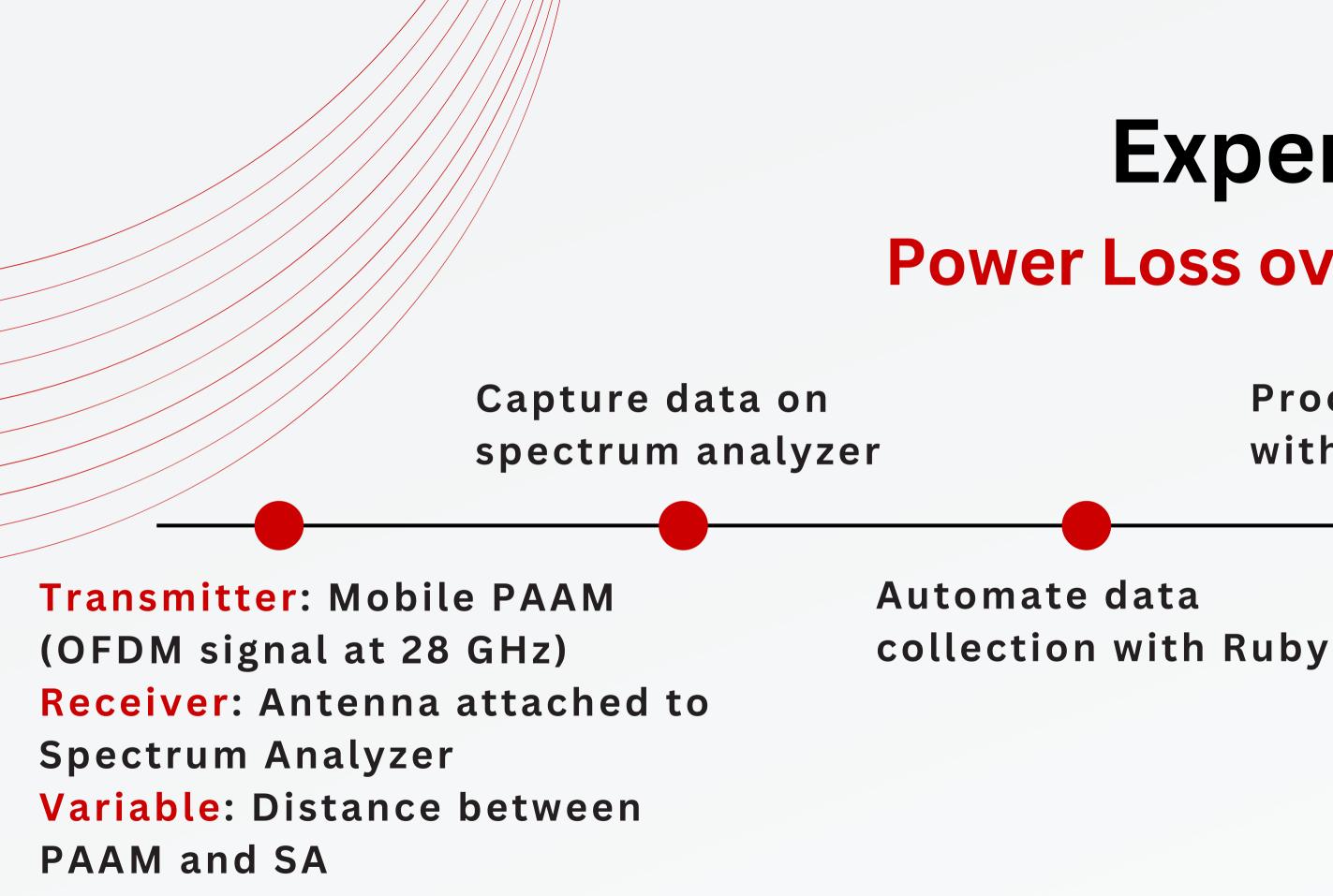


Software Python

- Script used to extract data from the flowgraph made in GNURadio
- SKLearn helps build representation of the data that was used
- ML(juggernaut) and training models







Experiment 1 Power Loss over Distance

Process and visualize with MATLAB

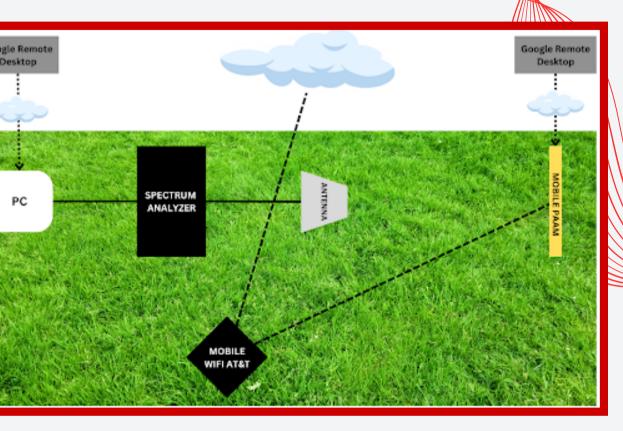
Conducted our experiment on grassy field outside of WINLAB. Figure 1

Transmitted signals from GNU Radio and Ο used a Ruby script to record frequency samples 100s of times.

• In between each transmission, mobile PAAM was moved further away from spectrum analyzer and temperature was recorded.









Experiment 1: Results

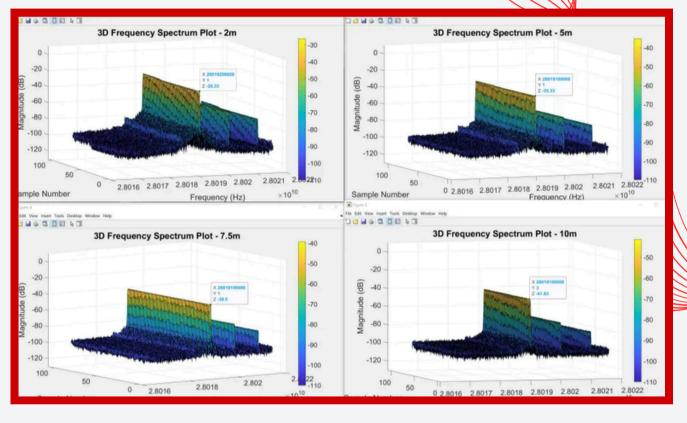
Results

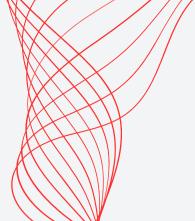
• Frequency data of transmitted signals.

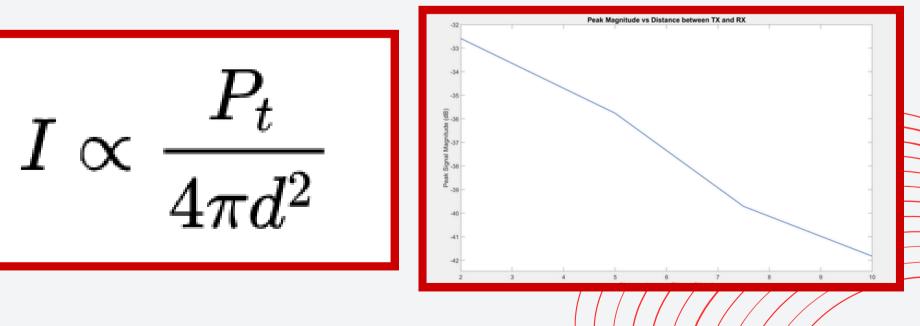
- The Peak magnitude between TX and RX as data points. Figure 2
- Indicating that the Channel Path loss is 1/4πd² ~ matching the theoretically expected relationship.

Problems

- Wifi disconnecting leading to battery and time waste
- O Mobile PAAM was not Calibrated leading to the I and Q







Experiment 1: Future

Future Plans

 Test this projects in various distances and frequencies such as 29 GHz, 30 GHz, and more.

• Incorporating the water Jug in this projects and placing it at various distance as well





Experiment 2 Detecting Water Interference

GNU Radio processing

Transmitter: PAAM #2 (OFDM signal at 28 GHz) **Receiver:** PAAM #1 Variable: Full water jug in front of PAAM #2

FFT pilot and sync word data extraction

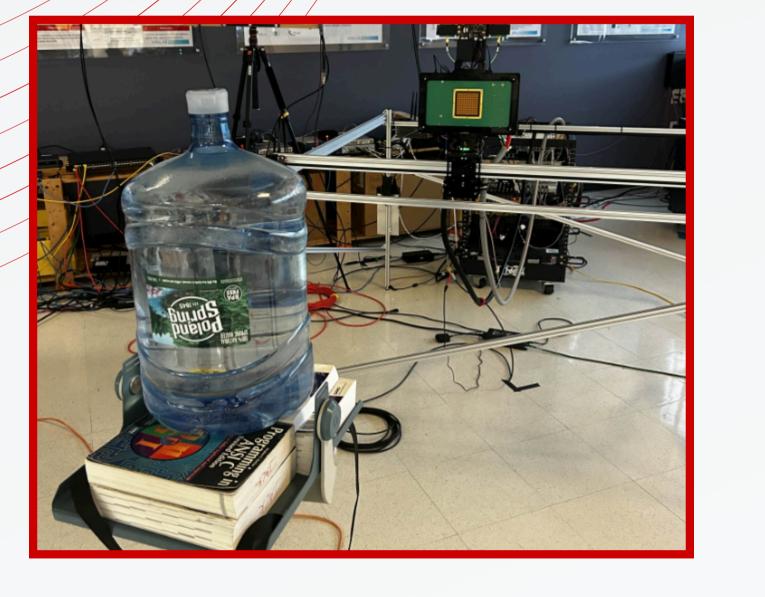
Dataset creation

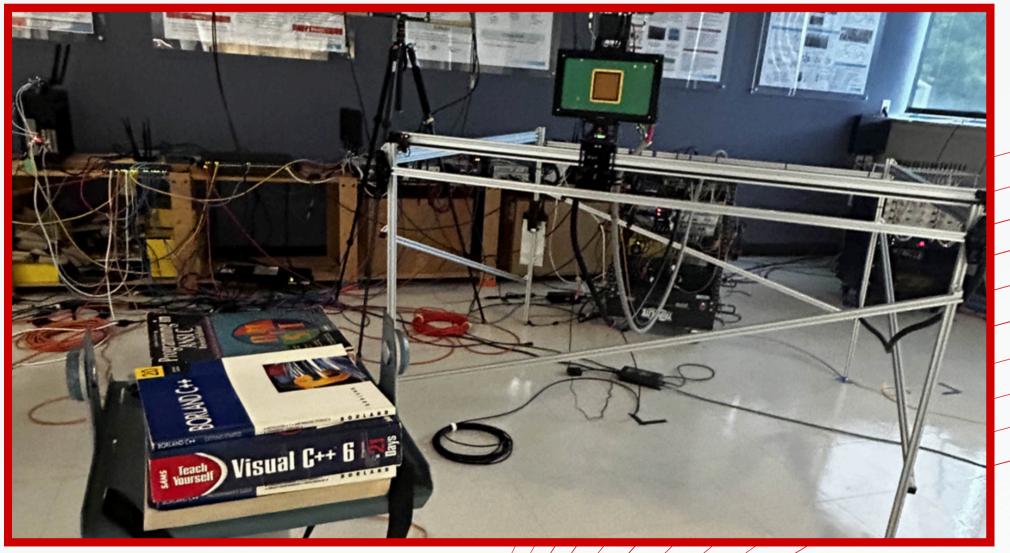
Classification



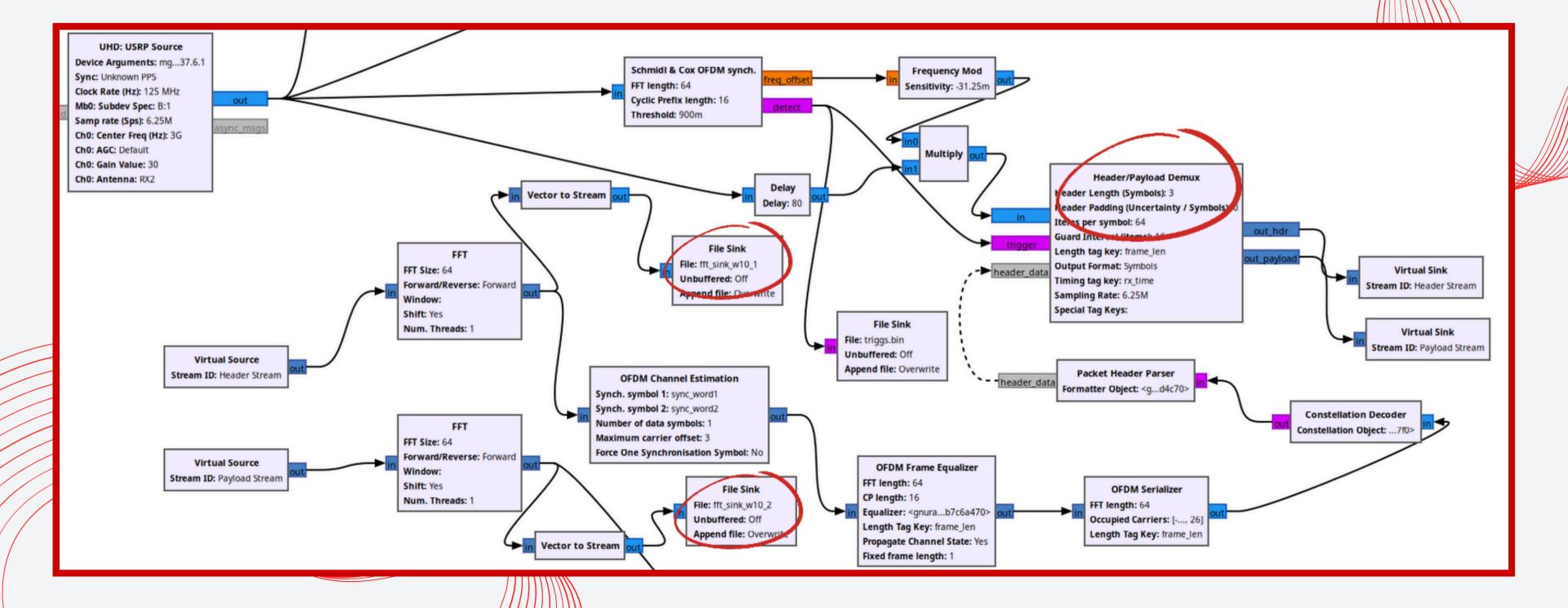


Experiment 2 Full Water Jug/ No Water Jug





GNU Radio Receiver flowgraph

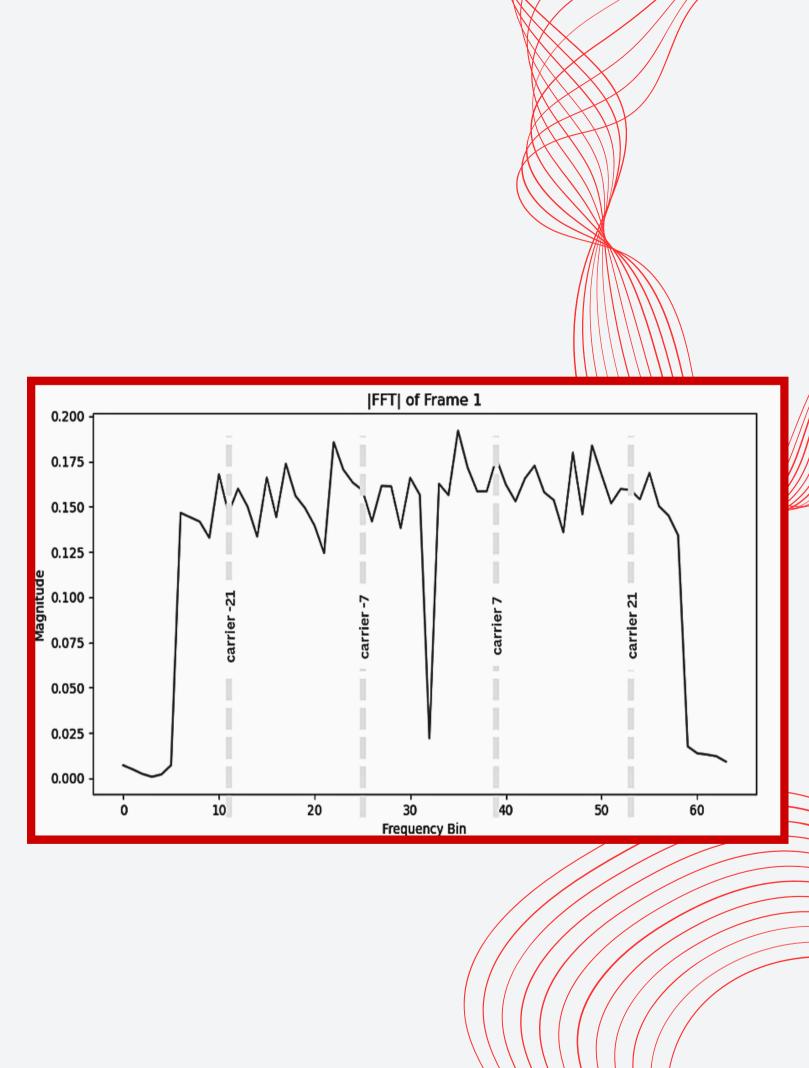




Creating the Dataset

• Extract pilot carrier data and sync word data from GNU Radio processing output

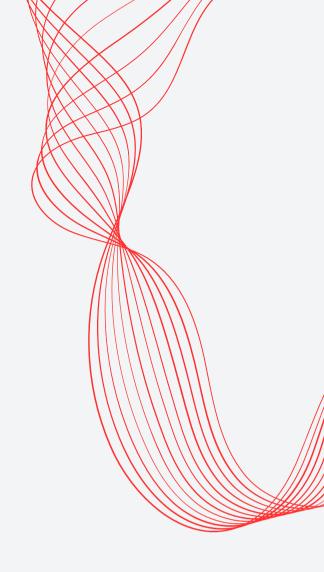
- Form dataset samples from groups of OFDM headers/payload with air/water labels
- Only keep phase information to improve model's generalization (encode into sine and cosine)



Data Processing: Probability of Accuracy

• Used a Python script to take binary RX data from GNU Radio and cross-correlate RX data with known TX message, to find a probability of accurate TX/RX of the message

• Automated the process to pipeline data from binary output to a usable format for ML models and human readability

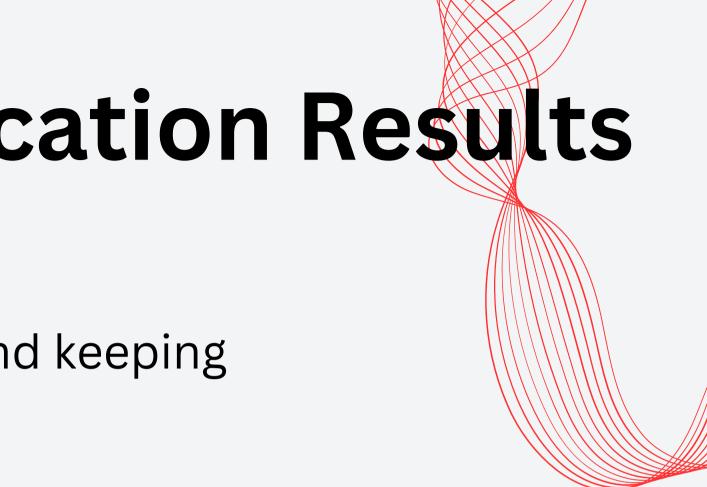




Initial Classification Results

• Tried various models after applying PCA and keeping most important components

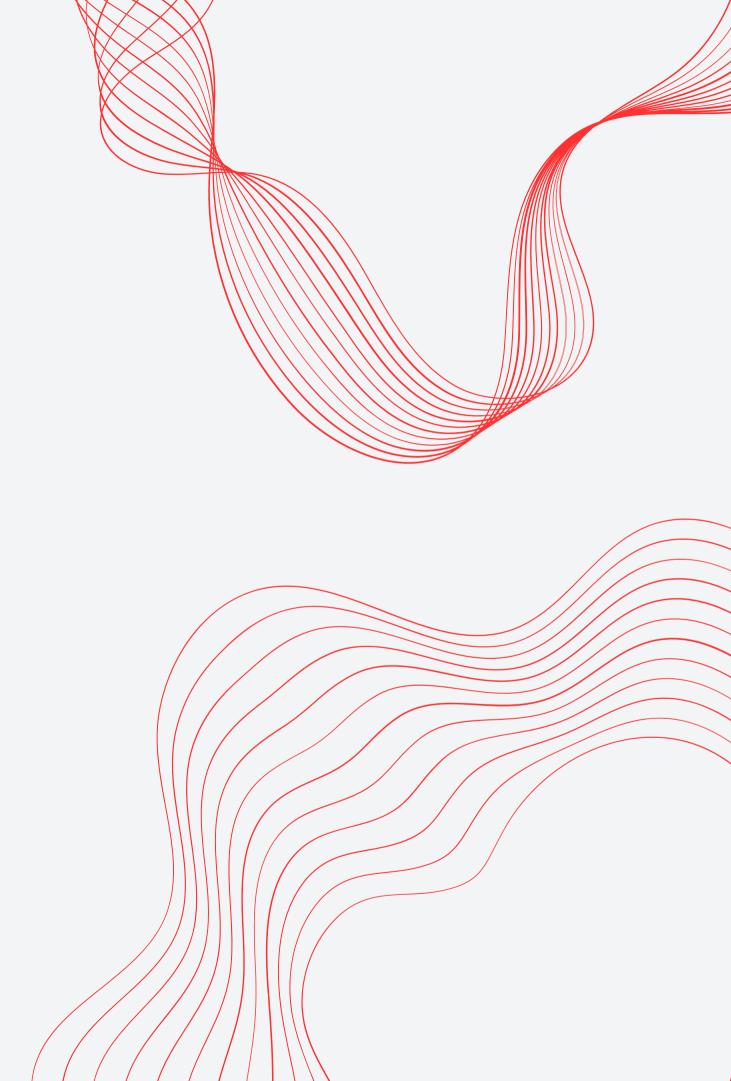
• Best F1-score of around 0.8: Random Forest Classifier, simple MLP, Gradient Boosting



More testing is needed Try to reason through the classification process

Future Work

- Continue outdoor experiments
- Diversification of Experimentation:
 - Variable number water jugs
 - Different distances
 - Different frequencies
 - Different setting
- Refine the post-processing pipeline → more accurate classification, achieve better generalization.
- Use model for practical identification of water interference
 - Actual rain conditions (?)



THANK YOU!

ANY QUESTIONS?

